



# A drone-borne gamma-ray spectrometer for soil texture mapping

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# gamma-ray spectrometer for soil mapping



- Gamma-ray sensors common practice in soil mapping
- Provide spatial covering information on soil texture
- Sensor gives nuclide-specific data
  - $^{40}\text{K}$  (potassium)
  - $^{238}\text{U}$  (uranium)
  - $^{232}\text{Th}$  (thorium)
  - $^{137}\text{Cs}$  (cesium)
- Calibration to soil parameters by soil samples

# Radiometric fingerprint

The idea:

- Soil is a mixture of different minerals
- The concentrations of (radioactive) chemical elements differ in all components
- These components can be measured in the field and in the laboratory

Fingerprint:

- The relation between (radioactive) chemical components and sediment composition
- Fingerprint can be used to translate field measurements to soil information



**Sand**

$^{40}\text{K}$  250 Bq/kg |  $^{238}\text{U}$  5 Bq/kg |  $^{232}\text{Th}$  5 Bq/kg

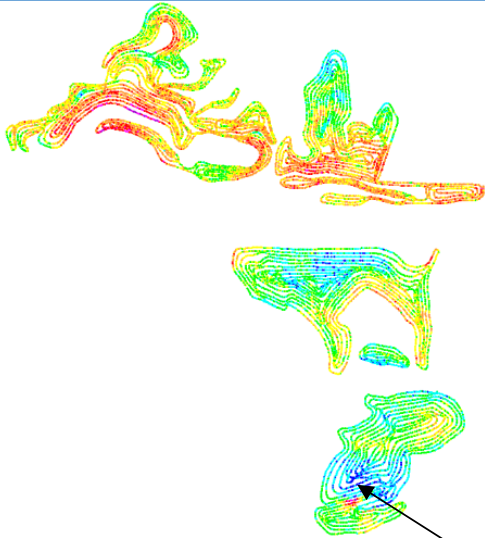


**Clay**

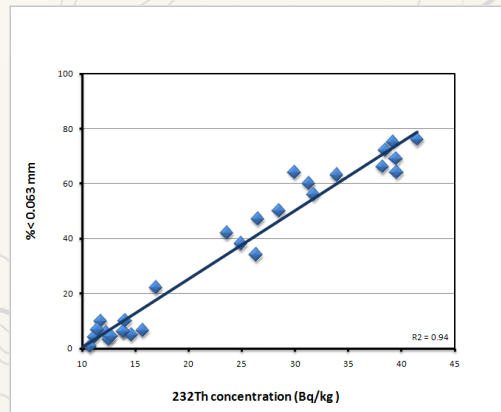
$^{40}\text{K}$  650 Bq/kg |  $^{238}\text{U}$  45 Bq/kg |  $^{232}\text{Th}$  45 Bq/kg

# From fielddata to maps

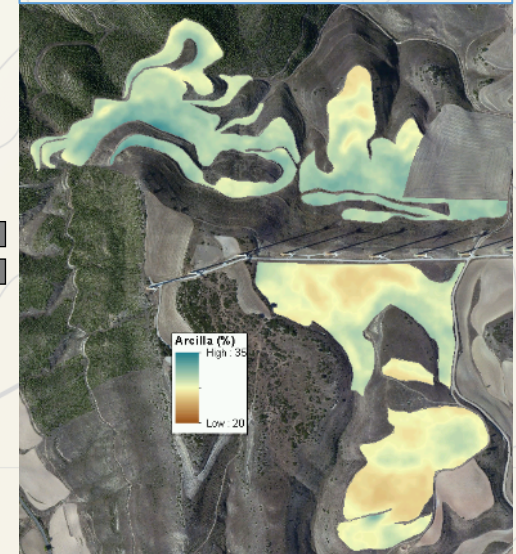
Gamma spectrometer (field)



Sample analyses (lab)



Clay content



Absolute concentrations are key!



# But what if.....



Hardware development and data modelling needed!

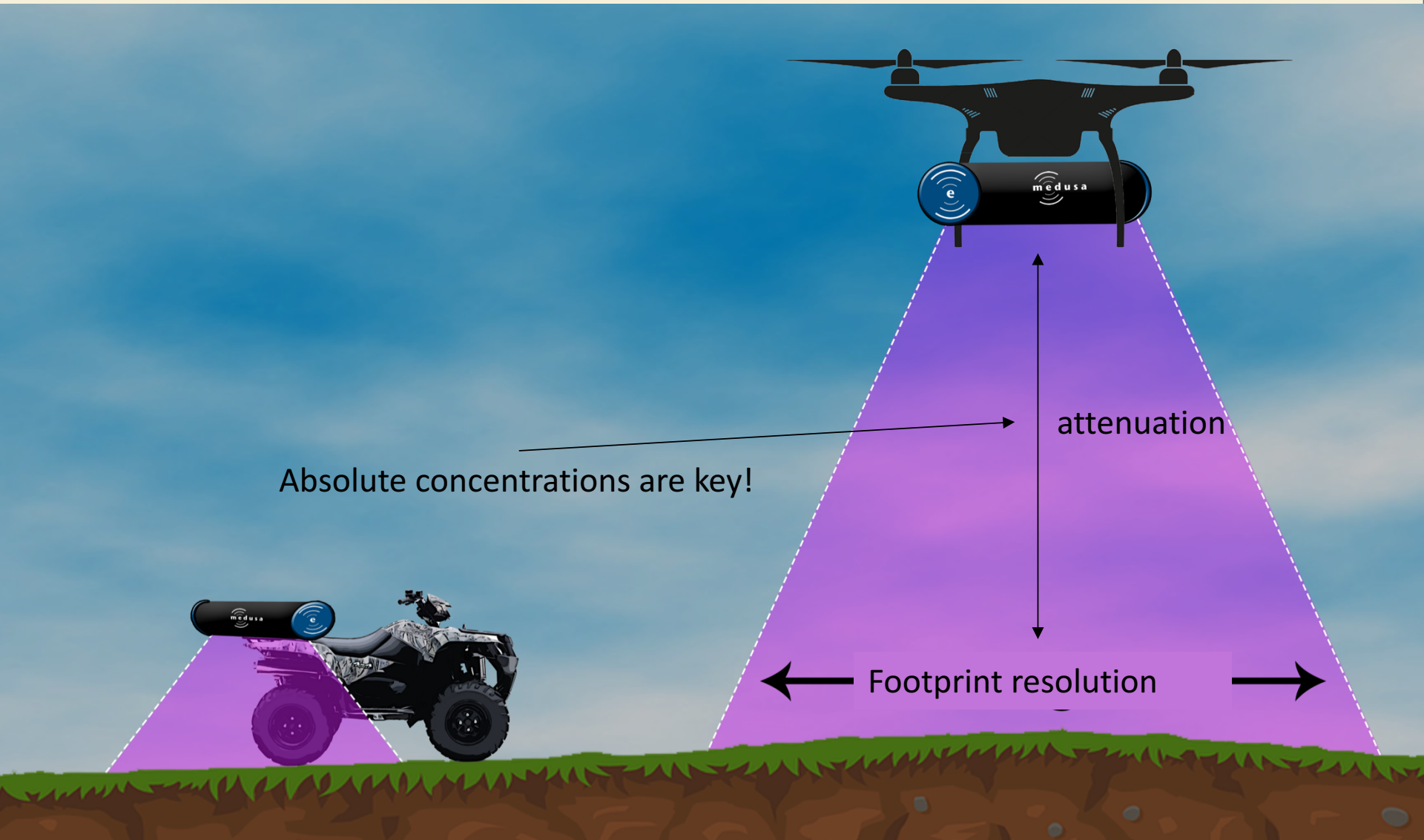
# Ground to Drone borne

## Hardware development

- Reduce
  - Size
  - Weight
  - Power consumption
- System should be autonomous



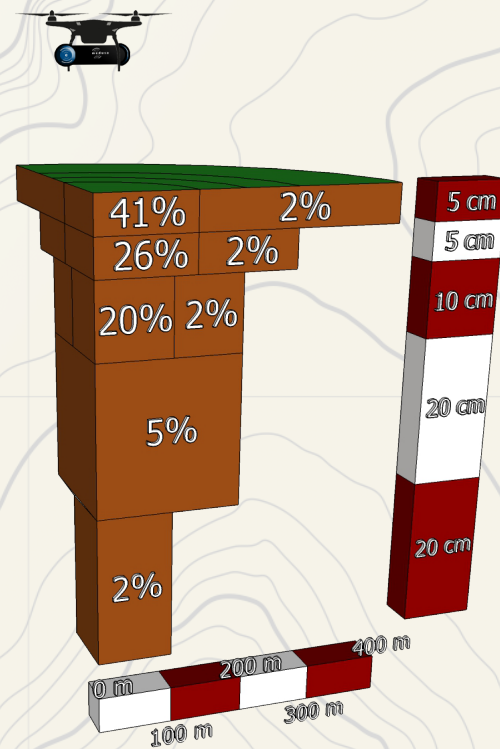
# Ground to Drone borne



## Data modelling attenuation



## Data modelling footprint



## Field testing





## Ground

- MS-2000, 2 L crystal
- Walking survey
- Elevation 0.8 m
- Measurement frequency of 1 Hz.
- Bare soil



## Drone

- MS-1000, 1 L crystal
- Drone survey
- Elevation 15 m
- Measurement frequency of 1 Hz.
- Vegetation started to grow



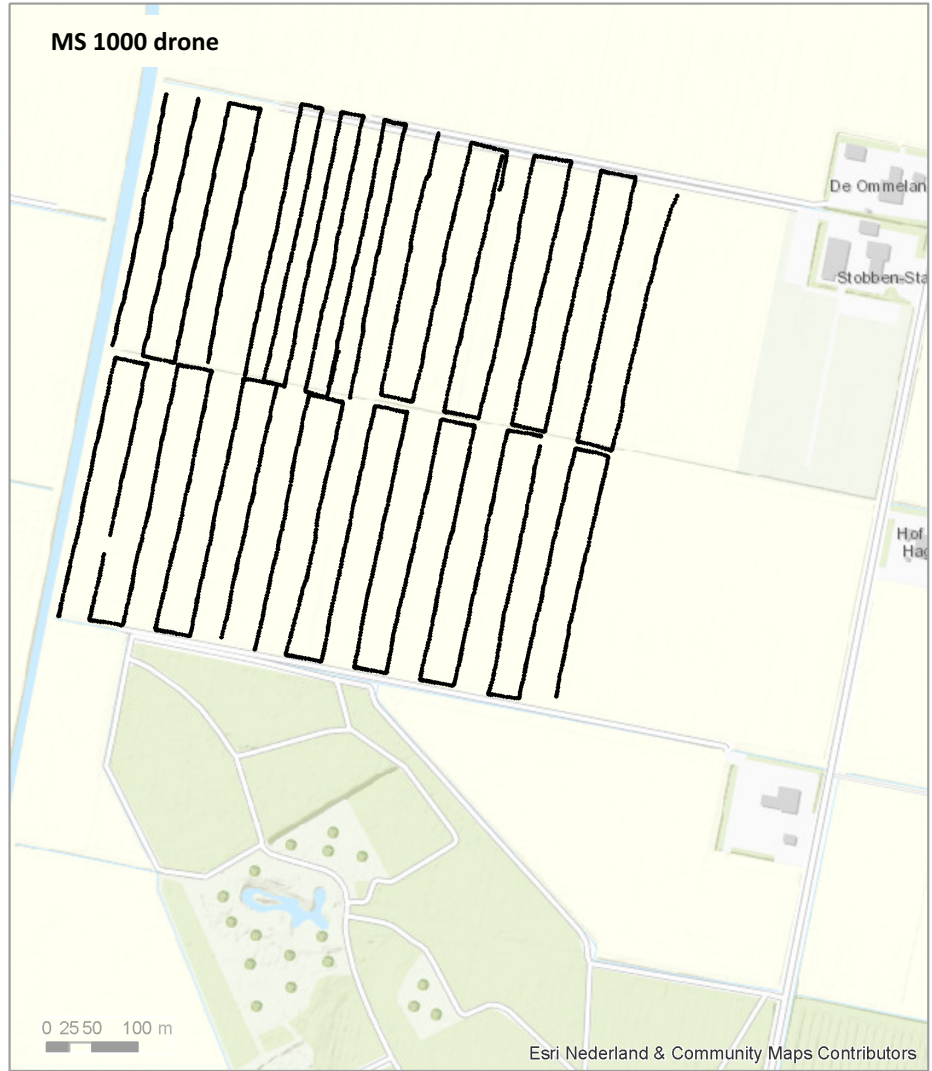
## Sampling

- 14 samples for calibration
- 44 samples for validation (stratified simple random sampling)
- Analysed on:
  - Radionuclides
  - Grain size
  - Clay and loam content
  - Organic matter

MS2000 Ground



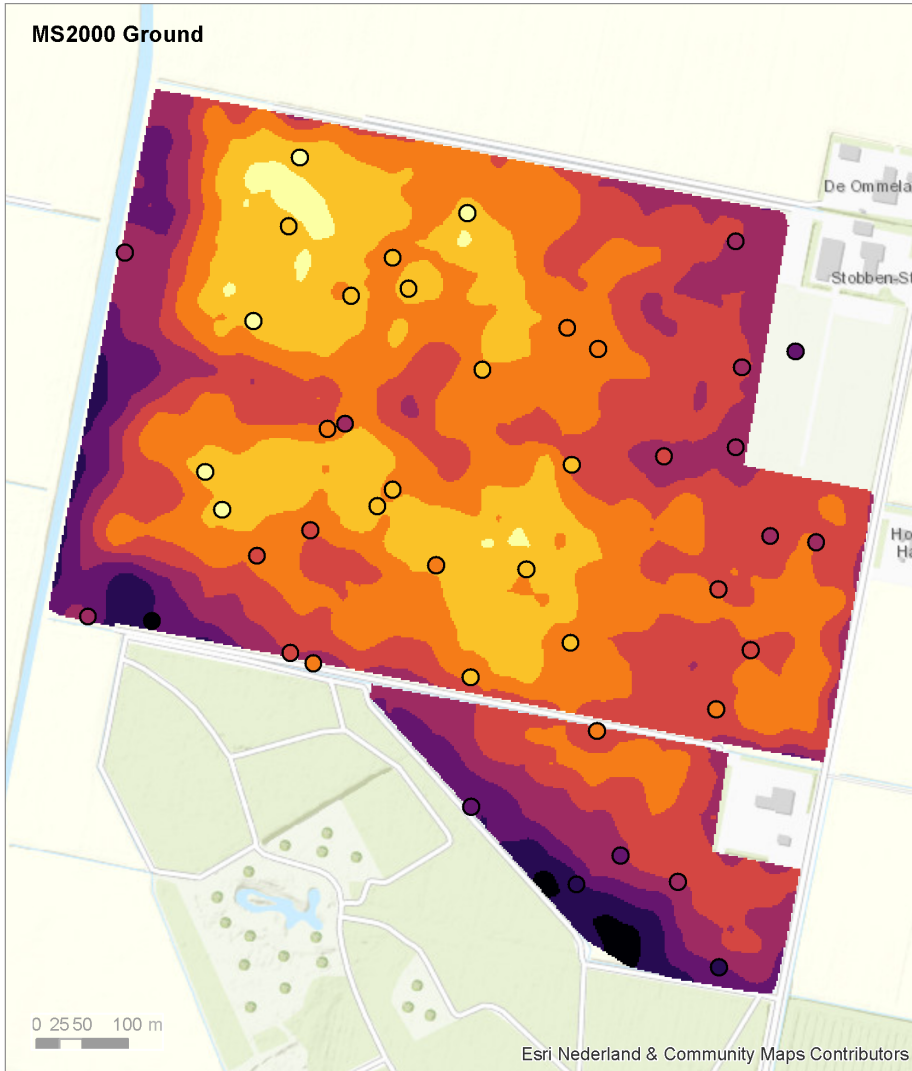
MS 1000 drone



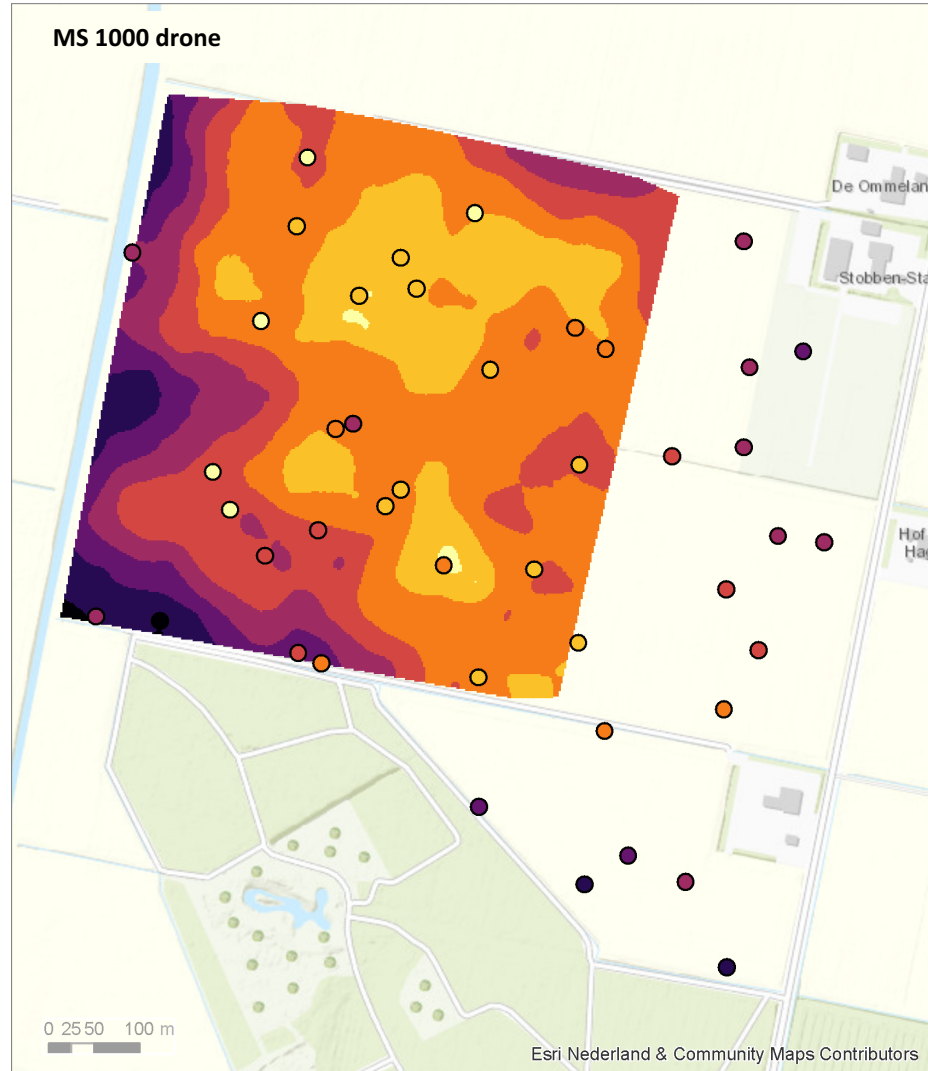
Survey lines



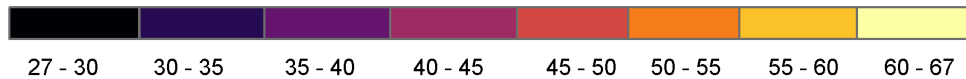
MS2000 Ground



MS 1000 drone



Grain size 0 - 50 µm (%)

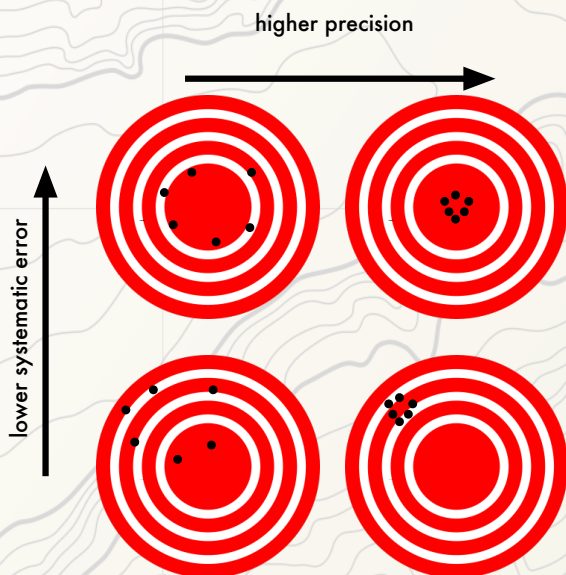


Validation



# 44 validation samples

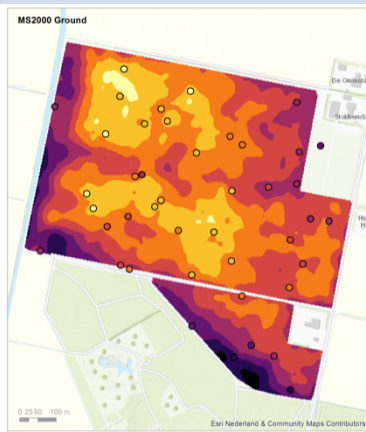
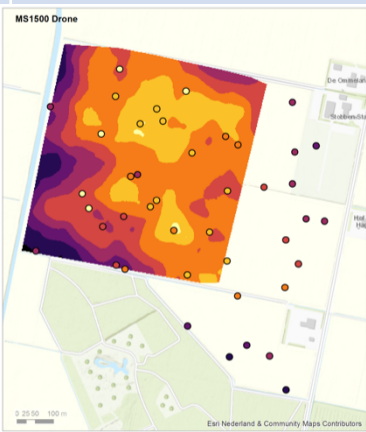
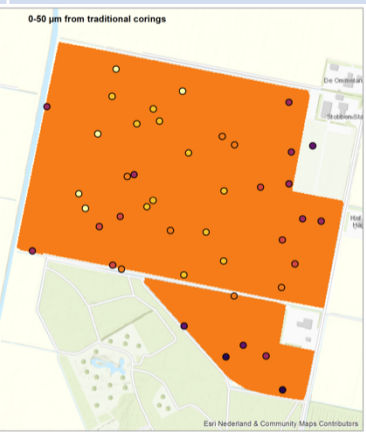
Map	Ground	Drone	Averaged
Range (0-50 $\mu\text{m}$ )	27%-66%	27%-66%	27%-66%
Systematic error	not significant	4.0% (1.2)	4 % (1)
Precision	6%	9.3%	9.9 %
Median absolute error	3.8%	6%	5.9%



SE: still some work needed to understand effects of elevation

P: probably effect of lower resolution due to elevation, smaller detector

# What if.. Benefits?

Map	Ground	Drone	Averaged
Median absolute error	4%	6%	6%
Cost/ha*	€120	€130	€80
Resolution			

\*costs based on pilot project, with 15 samples calibration, 12m line spacing

# Conclusions & outlook

- **Hardware**
  - A gamma-ray spectrometer with reduced size, weight, power consumption was developed.
  - This system is self-supporting
  - Successful test flights have been conducted
- **Data modelling**
  - First MCNP modelling and test measurement give promising results, will be improved.
- **Initial results field validation trials**
  - Good correspondence with predicted values and validation samples
  - A cost-benefit overview shows the trade off between statistical accuracy, costs, resolution
- **Outlook**
  - PhD traject started on improving data modelling, hardware development